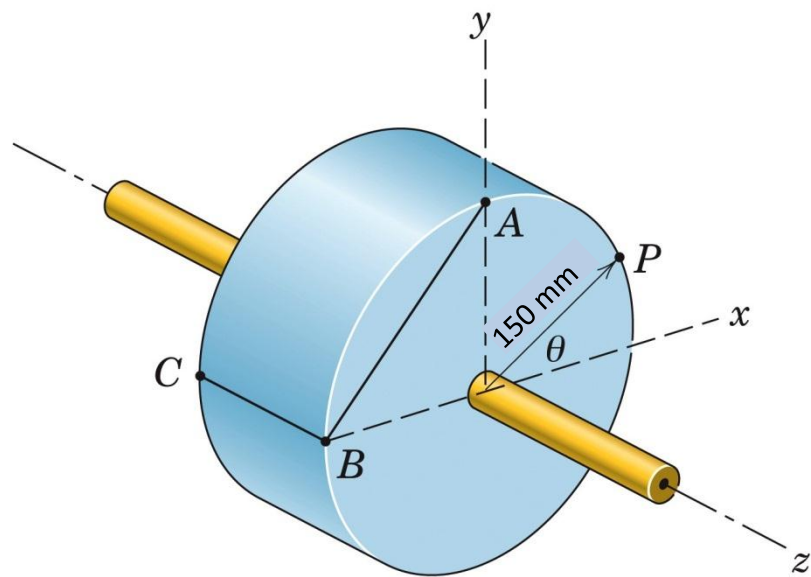


**ÇANKAYA UNIVERSITY – MECHANICAL ENGINEERING DEPARTMENT**  
**ME 204 – DYNAMICS – SPRING 2013**  
**HOMEWORK 4**  
**PLANE KINEMATICS OF RIGID BODIES**

Due Date: 1<sup>st</sup> Lecture Hour of Week 11

**PROBLEM 5/25**

The solid cylinder rotates about its z-axis. At the instant represented, point P on the rim has a velocity whose x-component is  $-1.28$  m/s, and  $\theta = 20^\circ$ . Determine the angular velocity  $\omega$  of line AB on the face of the cylinder. Does the element line BC have an angular velocity?



5/25

$$v_x = -1.28 \text{ m/s}$$

$$v = 1.28 / \sin 20^\circ = 3.74 \text{ m/s}$$

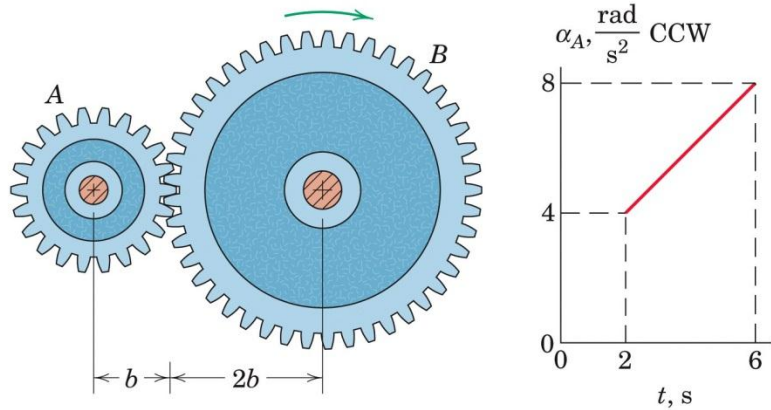
$$\omega = \frac{v}{r} = \frac{3.74}{0.150} = 24.9 \text{ rad/s CCW}$$

$$\underline{\omega = \omega_{AB} = \omega_{OP} = 24.9 \text{ k rad/s}}$$

Element BC remains parallel to z-axis  
 so has no angular velocity.

# **PROBLEM 5/28**

The design characteristics of a gear-reduction unit are under review. Gear  $B$  is rotating clockwise with a speed of 300 rev/min when a torque is applied to gear  $A$  at time  $t = 2$  s to give gear  $A$  a counterclockwise acceleration  $\alpha$  which varies with time for a duration of 4 seconds as shown. Determine the speed  $N_B$  of gear  $B$  when  $t = 6$  s.



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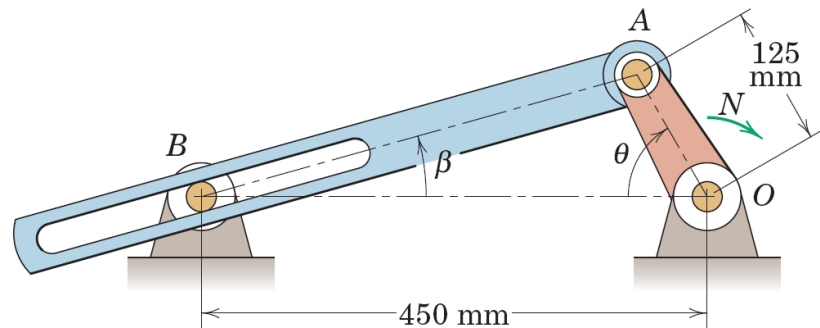

$$\text{For gear A, } \Delta\omega = \int_2^6 \alpha_A dt, \quad N_A = 2N_B$$

$$(N_A - 600) \frac{2\pi}{60} = \frac{4+8}{2} (6-2), \quad N_A = 600 + 229 = 829 \text{ rev/min}$$

$$\text{so at } t = 6 \text{ s, } N_B = \frac{829}{2} = \underline{415 \text{ rev/min}}$$

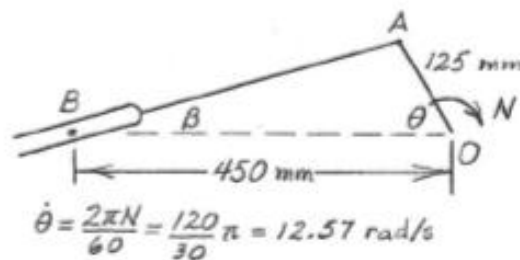
# **PROBLEM 5/53**

Angular oscillation of the slotted link is achieved by the crank  $OA$ , which rotates clockwise at the steady speed  $N = 120$  rev/min. Determine an expression for the angular velocity  $\dot{\beta}$  of the slotted link in terms of  $\theta$ .



5/53

$$\tan \beta = \frac{125 \sin \theta}{450 - 125 \cos \theta}$$



$$\dot{\theta} = \frac{2\pi N}{60} = \frac{120}{30} \pi = 12.57 \text{ rad/s}$$

$$\sec^2 \beta \dot{\beta} = \frac{(450 - 125 \cos \theta) 125 \dot{\theta} \cos \theta - 125 \sin \theta (125 \dot{\theta} \sin \theta)}{(450 - 125 \cos \theta)^2}$$

$$= \frac{56250 \cos \theta - 15625 \dot{\theta}}{(450 - 125 \cos \theta)^2}$$

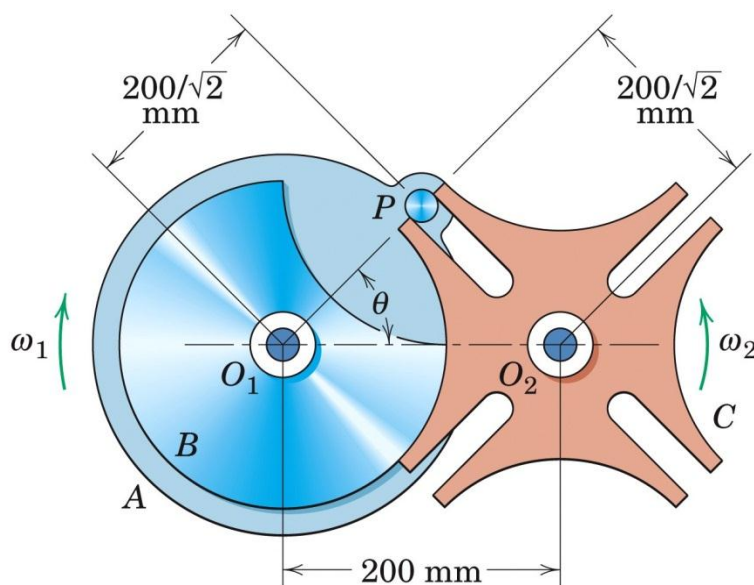
$$\dot{\beta} = \frac{56250 \cos \theta - 15625 \dot{\theta}}{(450 - 125 \cos \theta)^2} \cos^2 \beta$$

$$\text{But } \cos^2 \beta = \frac{(450 - 125 \cos \theta)^2}{450^2 + 125^2 - 2(450)(125) \cos \theta}$$

$$\text{So } \dot{\beta} = \frac{56250 \cos \theta - 15625}{218125 - 112500 \cos \theta} 12.57 \text{ or } \dot{\beta} = \frac{12.57 \cos \theta - 0.278}{1.939 - \cos \theta} \text{ rad/s}$$

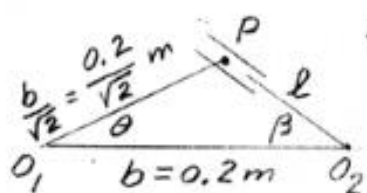
# **PROBLEM 5/56**

The Geneva wheel is a mechanism for producing intermittent rotation. Pin  $P$  in the integral unit of wheel  $A$  and locking plate  $B$  engages the radial slots in wheel  $C$ , thus turning wheel  $C$  one-fourth of a revolution for each revolution of the pin. At the engagement position shown,  $\theta = 45^\circ$ . For a constant clockwise angular velocity  $\omega_1 = 2 \text{ rad/s}$  of wheel  $A$ , determine the corresponding counterclockwise angular velocity  $\omega_2$  of wheel  $C$  for  $\theta = 20^\circ$ . (Note that the motion during engagement is governed by the geometry of triangle  $O_1O_2P$  with changing  $\theta$ .)



►5/56

$$\frac{b/\sqrt{2}}{\sin \beta} = \frac{b}{\sin(\pi - \theta - \beta)} = \frac{b}{\sin(\theta + \beta)}$$



$$\text{so } \sqrt{2} \sin \beta = \sin(\theta + \beta) \quad \text{--- (a)}$$

$$\sqrt{2} \dot{\beta} \cos \beta = (\dot{\theta} + \dot{\beta}) \cos(\theta + \beta)$$

$$\omega_2 = -\dot{\beta} = \dot{\theta} \frac{\cos(\theta + \beta)}{\cos(\theta + \beta) - \sqrt{2} \cos \beta} \quad \text{--- (b)}$$

$$\text{From (a) } \sin \beta (\sqrt{2} - \cos \theta) = \sin \theta \cos \beta, \quad \tan \beta = \frac{\sin \theta}{\sqrt{2} - \cos \theta}$$

$$\text{For } \theta = 20^\circ, \quad \beta = \tan^{-1} \frac{0.3420}{\sqrt{2} - 0.9397} = \tan^{-1} 0.7208 = 35.8^\circ$$

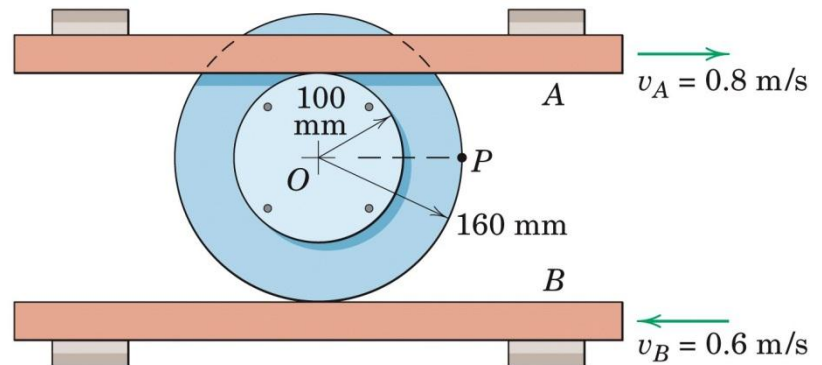
& for  $\dot{\theta} = -2 \text{ rad/s}$ , Eq. (b) gives

$$\omega_2 = -2 \frac{\cos(20^\circ + 35.8^\circ)}{\cos(20^\circ + 35.8^\circ) - \sqrt{2} \cos 35.8^\circ} = -2 \frac{0.5623}{-0.5849}$$

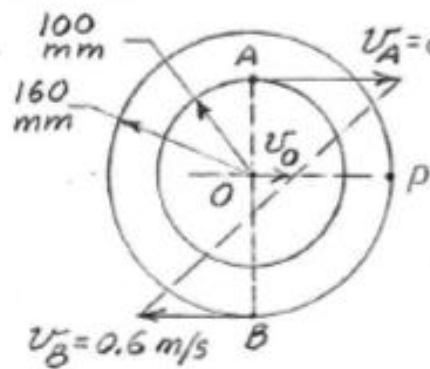
$$\omega_2 = 1.923 \text{ rad/s}$$

# **PROBLEM 5/75**

Each of the sliding bars  $A$  and  $B$  engages its respective rim of the two riveted wheels without slipping. Determine the magnitude of the velocity of point  $P$  for the position shown.



5/75



$$\omega = \frac{v_A + v_B}{AB} = \frac{0.8 + 0.6}{0.26} = 5.38 \frac{\text{rad}}{\text{s}} \quad \text{CW}$$

$$v_O = v_A - AO\omega = 0.8 - 0.1(5.38) = 0.262 \frac{\text{m}}{\text{s}}$$

$$v_P = v_O + v_{P/O}$$

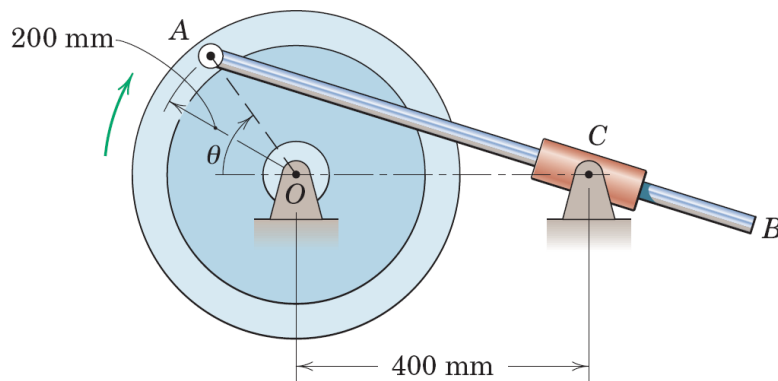
$$v_{P/O} = PO\omega = 0.16(5.38) = 0.862 \frac{\text{m}}{\text{s}}$$

$$v_P = \sqrt{0.262^2 + 0.862^2} = 0.900 \frac{\text{m}}{\text{s}}$$



# **PROBLEM 5/84**

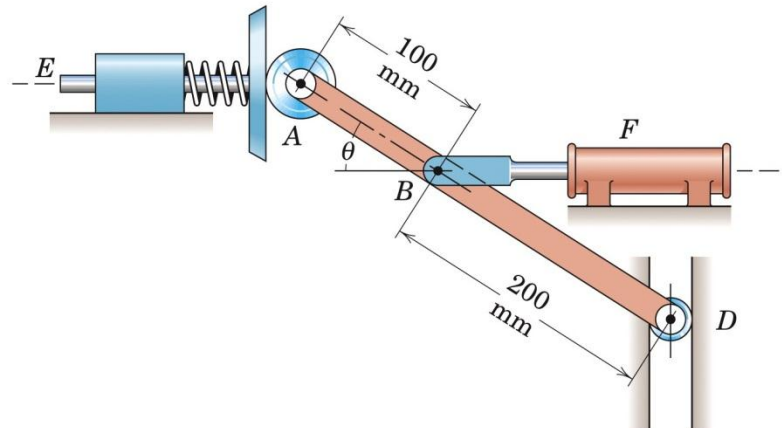
The flywheel turns clockwise with a constant speed of 600 rev/min, and the connecting rod  $AB$  slides through the pivoted collar at  $C$ . For the position  $\theta = 45^\circ$ , determine the angular velocity  $\omega_{AB}$  of  $AB$  by using the relative-velocity relations. (Suggestion: Choose a point  $D$  on  $AB$  coincident with  $C$  as a reference point whose direction of velocity is known.)



$$\begin{aligned}
 & \text{600 rev/min} \\
 & \text{0.2m} \\
 & 45^\circ \\
 & \text{O} \\
 & \text{B} \\
 & \text{C} \\
 & \text{D} \\
 & \text{0.4m} \\
 & \vec{v}_A = \vec{v}_D + \vec{v}_{A/D} \\
 & v_A = r\omega = \frac{0.2 \cdot 600(2\pi)}{60} = 12.56 \text{ m/s} \\
 & \beta = \tan^{-1} \frac{0.2 \sin 45^\circ}{0.4 + \cos 45^\circ} = 14.64^\circ \\
 & v_{A/D} = 12.56 \sin (45^\circ + 14.64^\circ) = 10.84 \text{ m/s} \\
 & \omega_{AB} = \omega_{AD} = \frac{v_{A/D}}{AD} \\
 & AD = \frac{0.2 \cos 45^\circ}{\sin 14.64^\circ} = 0.560 \text{ m} \\
 & \omega_{AB} = \frac{10.84}{0.560} = 19.38 \text{ rad/sec CW}
 \end{aligned}$$

# **PROBLEM 5/108**

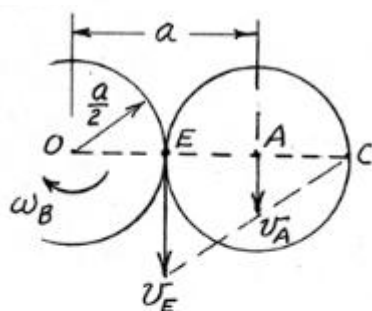
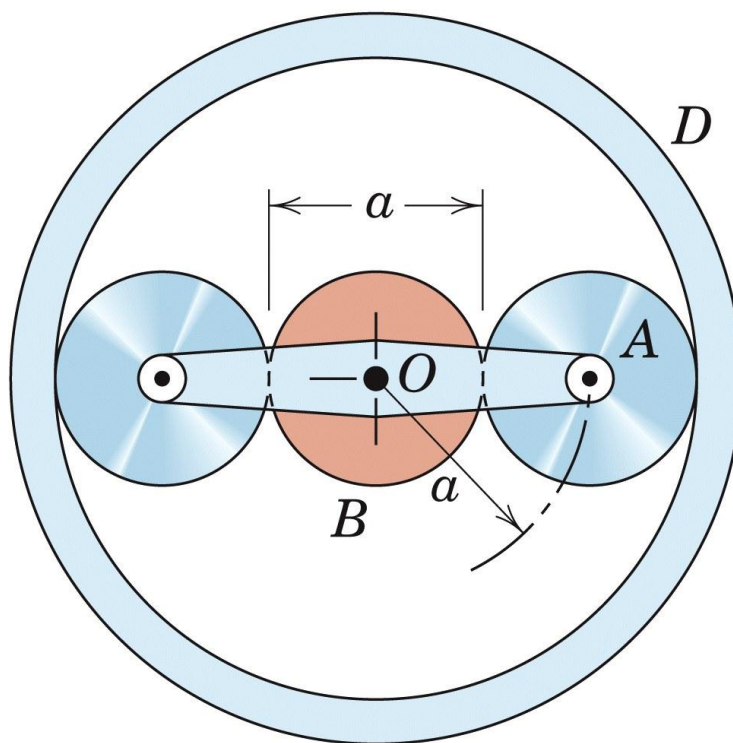
Horizontal oscillation of the spring-loaded plunger  $E$  is controlled by varying the air pressure in the horizontal pneumatic cylinder  $F$ . If the plunger has a velocity of 2 m/s to the right when  $\theta = 30^\circ$ , determine the downward velocity  $v_D$  of roller  $D$  in the vertical guide and find the angular velocity  $\omega$  of  $ABD$  for this position.



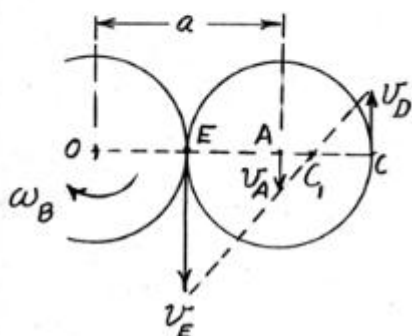
$$\begin{aligned}
 & \vec{CB} = 0.1 \text{ m} = \vec{AB}, \quad 2\beta + (180 - 60) = 180 \\
 & \beta = 30^\circ, \quad \gamma = 30^\circ \\
 & AC = 2(0.1) \cos 30^\circ = 0.1732 \text{ m} \\
 & v_A = \frac{2}{\cos 30^\circ} = 2.31 \text{ m/s} \\
 & \omega = \frac{v_A}{AC} = \frac{2.31}{0.1732} = 13.33 \frac{\text{rad}}{\text{s}} \\
 & v_D = \vec{CD} \omega = 0.2 \cos 30^\circ (13.33) \\
 & \quad = 2.31 \text{ m/s}
 \end{aligned}$$

PROBLEM 5/120

The shaft at  $O$  drives the arm  $OA$  at a clockwise speed of 90 rev/min about the fixed bearing at  $O$ . Use the method of the instantaneous center of zero velocity to determine the rotational speed of gear  $B$  (gear teeth not shown) if (a) ring gear  $D$  is fixed and (b) ring gear  $D$  rotates counterclockwise about  $O$  with a speed of 80 rev/min.



$$\begin{aligned} (a) \quad v_A &= \omega_{OA} a \\ v_E &= 2v_A = 2a\omega_{OA} \\ \omega_B &= \frac{v_E}{a/2} = \frac{2a\omega_{OA}}{a/2} = 4(90) \\ &= \underline{360 \text{ rev/min}} \end{aligned}$$

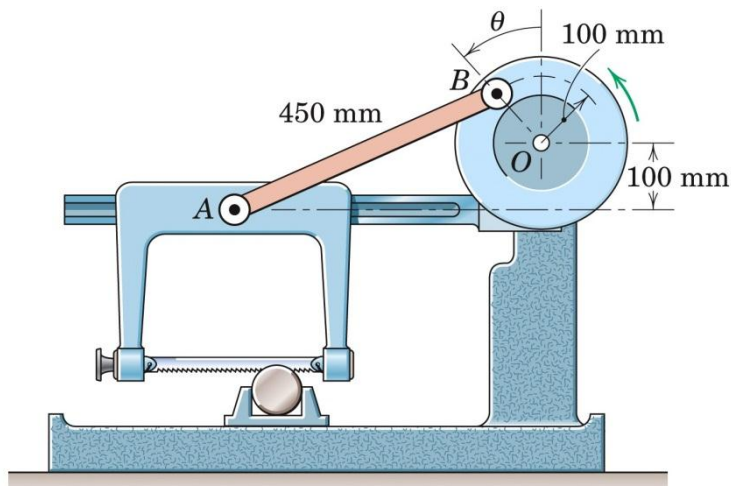


$$\begin{aligned} (b) \quad v_D &= \overline{OC} \omega_D = \frac{3a}{2} 80 = 120a \\ v_A &= \overline{OA} \omega_{OA} = 90a \\ \frac{v_A + v_D}{a} &= \frac{v_E - v_A}{a}, \quad v_E = v_D + 2v_A \\ &= 300a \\ \omega_{OE} = \omega_B &= \frac{v_E}{a/2} = \frac{300a}{a/2} = \underline{600 \frac{\text{rev}}{\text{min}}} \end{aligned}$$



# **PROBLEM 5/153**

The elements of a power hacksaw are shown in the figure. The saw blade is mounted in a frame which slides along the horizontal guide. If the motor turns the flywheel at a constant counterclockwise speed of 60 rev/min, determine the acceleration of the blade for the position where  $\theta = 90^\circ$ , and find the corresponding angular acceleration of the link AB.

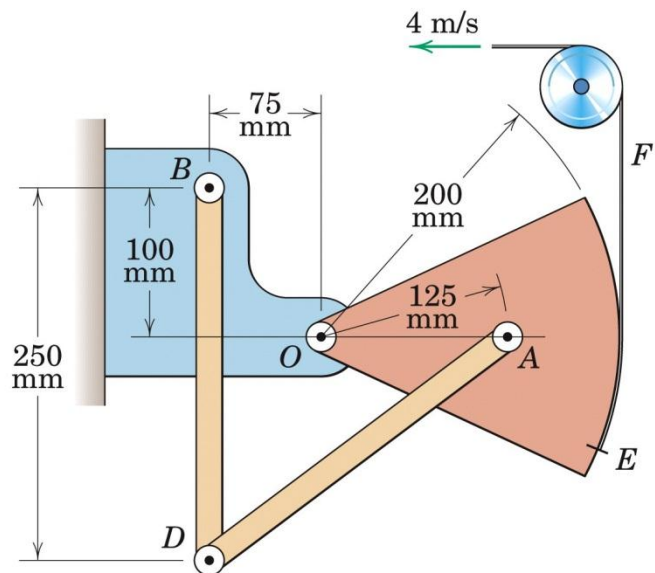


5/153  $C =$  instantaneous center of zero velocity for AB

$\omega_{AB} = \frac{v_B}{CB} = \frac{OB \omega}{CB}$   
 $= \frac{100}{439} \frac{60(2\pi)}{60} = 1.432 \frac{\text{rad}}{\text{s}}$   
 $\omega = 60 \text{ rev/min}$   
 $a_B = (a_B)_n = 100(2\pi)^2 = 3950 \text{ mm/s}^2$   
 $(a_{A/B})_n = 450(1.432)^2 = 923 \text{ mm/s}^2$   
 $a_A = a_B + (a_{A/B})_n + (a_{A/B})_t$   
 $\beta = \tan^{-1} \frac{100}{439} = 12.82^\circ$   
 $a_B = 3950 \text{ mm/s}^2$   
 $(a_{A/B})_n = 923 \text{ mm/s}^2$   
 $(a_{A/B})_t = 923 \tan 12.82 = 923 \frac{100}{439} = 210 \text{ mm/s}^2$   
 $\alpha_{AB} = \frac{(a_{A/B})_t}{AB} = \frac{210}{450} = 0.467 \text{ rad/s}^2 \text{ CCW}$   
 $a_A = 3950 + 923 \cos 12.82^\circ + 210 \sin 12.82^\circ = 4890 \text{ mm/s}^2$   
or  $a_A = 4.89 \text{ m/s}^2$

# **PROBLEM 5/154**

The mechanism of Prob. 5/115 is repeated here where the flexible band  $F$  attached to the sector at  $E$  is given a constant velocity of 4 m/s as shown. For the instant when  $BD$  is perpendicular to  $OA$ , determine the angular acceleration of  $BD$ .



$U = 4 \text{ m/s const.}$  From Prob. 5/118  
 $U_A = 2.5 \frac{\text{m}}{\text{s}}, U_D = 1.875 \frac{\text{m}}{\text{s}}$   
 $\omega_{AD} = 12.5 \text{ rad/s}$

Dimensions in mm  
 $\theta = \tan^{-1} \frac{200}{150} = 53.1^\circ$   
 $\bar{AD} = 250 \text{ mm}$

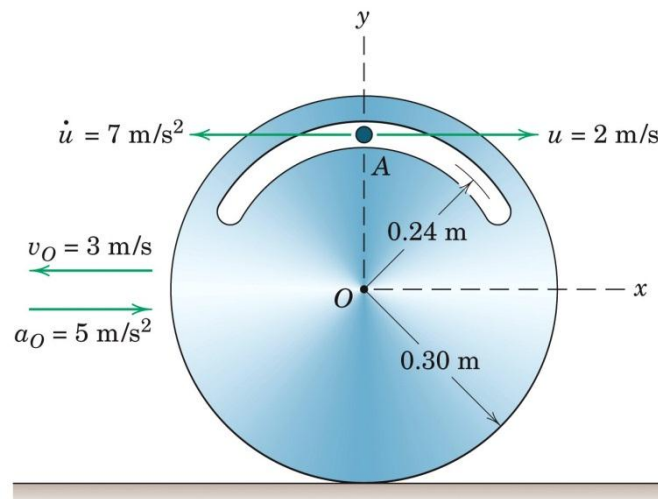
$\underline{a}_D = \underline{a}_A + \underline{a}_{D/A}$   
 $(a_D)_n = \frac{U_D^2}{\bar{BD}} = \frac{1.875^2}{0.250} = 14.06 \text{ m/s}^2$   
 $a_A = (a_A)_n = \frac{U_A^2}{\bar{OA}} = \frac{2.5^2}{0.125} = 50 \text{ m/s}^2$   
 $(a_{D/A})_n = \bar{AD} \omega_{AD}^2 = 0.250(12.5)^2 = 39.1 \text{ m/s}^2$

Solution of polygon gives  $(a_{D/A})_t = 11.72 \text{ m/s}^2$   
 $(a_D)_t = 11.72 \text{ m/s}^2$   
 $\alpha_{BD} = (a_D)_t / \bar{BD}$   
 $= \frac{11.72}{0.25} = 46.9 \frac{\text{rad}}{\text{s}^2} \text{ CW}$

$\theta = 36.9^\circ$   
 $a_A = (a_A)_n = 50 \text{ m/s}^2$

# **PROBLEM 5/162**

The disk rolls without slipping on the horizontal surface, and at the instant represented, the center  $O$  has the velocity and acceleration shown in the figure. For this instant, the particle  $A$  has the indicated speed  $u$  and time-rate-of-change of speed  $\dot{u}$ , both relative to the disk. Determine the absolute velocity and acceleration of particle  $A$ .



For the coordinates  $\begin{matrix} y \\ \uparrow \\ x \end{matrix}$ , The no-slip constraints are  $v_O = -r\omega$  &  $a_O = -r\alpha$ . So

$$\omega = -\frac{v_O}{r} = -\frac{-3}{0.30} = 10 \text{ rad/s}$$

$$\alpha = -\frac{a_O}{r} = -\frac{5}{0.30} = -16.67 \text{ rad/s}^2$$

Use the frame  $Oxy$  as disk-fixed.

$$(5/12): \underline{v}_A = \underline{v}_O + \underline{\omega} \times \underline{r} + \underline{v}_{rel}$$

$$(5/14): \underline{a}_A = \underline{a}_O + \underline{\alpha} \times \underline{r} + \underline{\omega} \times (\underline{\omega} \times \underline{r}) + 2\underline{\omega} \times \underline{v}_{rel} + \underline{a}_{rel}$$

$$\text{Ingredients: } \begin{cases} \underline{v}_O = -3\underline{i} \text{ m/s} \\ \underline{a}_O = 5\underline{i} \text{ m/s}^2 \\ \underline{\omega} = 10\underline{k} \text{ rad/s} \\ \underline{\alpha} = -16.67\underline{k} \text{ rad/s}^2 \end{cases} \quad \begin{cases} \underline{r} = 0.24\underline{j} \text{ m} \\ \underline{v}_{rel} = 2\underline{i} \text{ m/s} \\ \underline{a}_{rel} = -7\underline{i} - \frac{2^2}{0.24}\underline{j} \\ \quad = -7\underline{i} - 16.67\underline{j} \text{ m/s}^2 \end{cases}$$

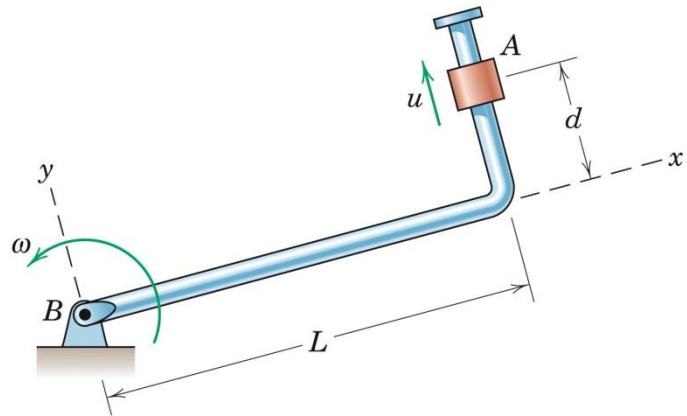
Substitute into (5/12) & (5/14) & simplify:

$$\underline{v}_A = -3.4\underline{i} \text{ m/s}$$

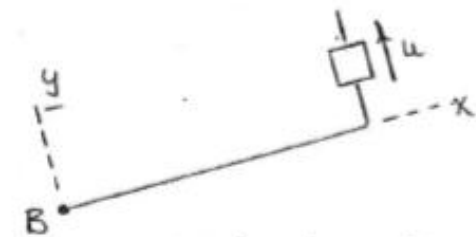
$$\underline{a}_A = 2\underline{i} - 0.667\underline{j} \text{ m/s}^2$$

# **PROBLEM 5/165**

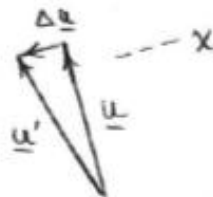
The small cylinder  $A$  is sliding on the bent bar with speed  $u$  relative to the bar as shown. Simultaneously, the bar is rotating with angular velocity  $\omega$  about the fixed pivot  $B$ . Take the  $x$ - $y$  axes to be fixed to the bar and determine the Coriolis acceleration of the slider for the instant represented. Interpret your result.



$$\begin{aligned} \underline{a}_{\text{cor}} &= 2 \underline{\omega} \times \underline{v}_{\text{rel}} \\ &= 2 \omega \underline{k} \times u \underline{j} = \underline{-2\omega u \underline{i}} \end{aligned}$$



Change-of-direction effect is in  $-x$  direction:



Change-of-magnitude effect is in  $-x$  direction:

